



## TUTORIAL

### Title

Unleashing the Power of Airborne Computing in UAV Systems

### Organizer(s)

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### Duration

FOUR-Hours

### Structure

1. Introduction (30min)
  - a. Market Dynamics and UAV Innovations
  - b. Regulatory Landscape and Policy Implications
  - c. Exploration of UAV Applications
  - d. UAV Functionalities and the Imperative for Onboard Computing
  - e. The Drive Towards UAV-based Airborne Computing
  - f. NSF Supports and Project Timeline
2. Deep Dive into UAV Applications (60min)
  - a. Categorizing UAV Applications
  - b. Layered Framework for Analysis and Design
    - i. Mission Layer
    - ii. Task Layer
    - iii. Function Layer
  - c. The Role of Computing in UAV Functions
    - i. Control
    - ii. Communication
    - iii. Networking



- iv. Computing
  - d. Spotlight on Computing-Driven UAV Applications
    - i. Precision Agriculture through UAVs
    - ii. UAVs in Emergency Response
- 3. Crafting the Future: Design Guidelines and Platforms (90min)
  - a. System Overview
  - b. Key Components
    - i. Quadcopter Unit
    - ii. Control Mechanisms
    - iii. Communication Infrastructure
    - iv. Computing Core
  - c. Prototype Insights
    - i. Processor Selection and Carrier Board Design
    - ii. Directional Antenna System Architecture
  - d. Advanced UAV Functions Enhanced by Computing
    - i. Reinforcement Learning for Antenna Orientation
    - ii. Real-time Object Detection with Deep Learning
    - iii. Advanced Coded Distributed Computing
    - iv. Coded Federated Learning
    - v. Software-defined radio-powered cellular base station
- 4. Concluding Remarks and Interactive Discussions (60min)
  - a. Recap and Reflections
  - b. Future Horizons and Open Challenges
    - i. Integration of UAVs in 5G/6G Non-Terrestrial Networks
    - ii. Facilitating UAV-based edge computing
    - iii. Fully integrating Artificial Intelligence in UAV-based airborne computing
  - c. Gathering Feedback for Continuous Improvement

## Outline

Unmanned Aerial Vehicles (UAVs) have emerged as a transformative force in technology, capturing the attention of industries, government agencies, and academia. Supported by the National Science Foundation (NSF), our research initially spanned from 2017 to 2022 under a major NSF project and has now entered its second phase with a new award starting in 2023. Despite advancements in UAV control, communication, networking, and computing, fully unlocking the potential of airborne computing remains a significant challenge. This tutorial addresses this gap, laying the foundation for a new era of UAV-centric airborne computing.

This tutorial will: (1) explore current and emerging UAV applications, analyzing their complexities; (2) present real-world case studies demonstrating how airborne computing transforms UAV functionalities; (3) provide essential design strategies for next-generation UAV systems enhanced by airborne computing; (4) showcase our cutting-edge UAV-based airborne computing platform and latest prototype; and (5) explore pioneering UAV functions, encompassing reinforcement-learning guided antenna positioning, coding-driven distributed computing and federated learning, software-defined radio-powered cellular base stations, and deep-learning-enhanced object detection.



Aligned with IEEE SMC 2025's theme, this tutorial highlights the pivotal role of airborne computing in advancing UAV design and enabling innovative applications. Attendees will leave with a deeper understanding of the challenges, innovations, and future opportunities in UAV-based airborne computing.